

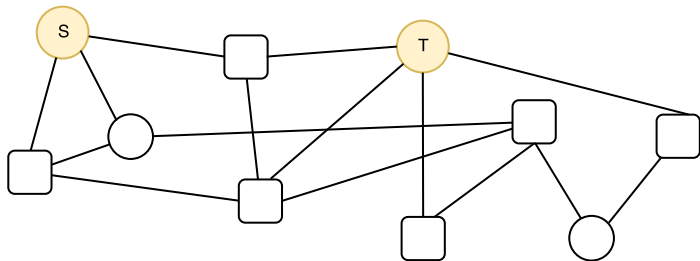
Walking through the Cloud: Routing of Virtualized Network Functions

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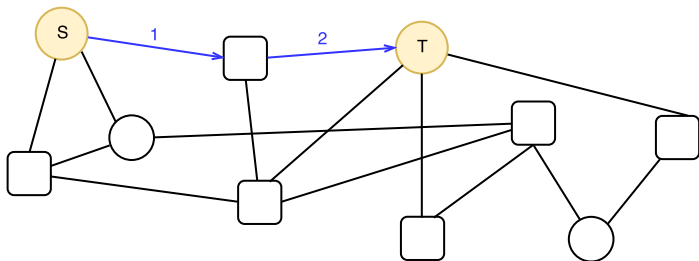
ALGO CLOUD, 2017

A Routing Problem



A Routing Problem

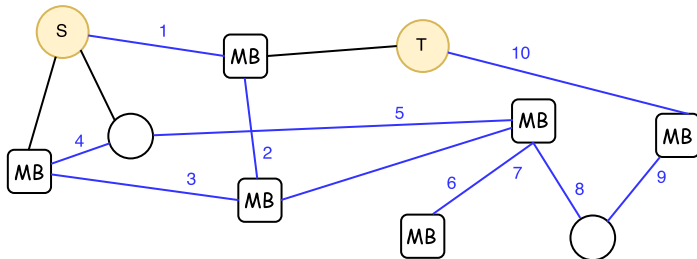
the usual routing



A Routing Problem

new: middleboxes

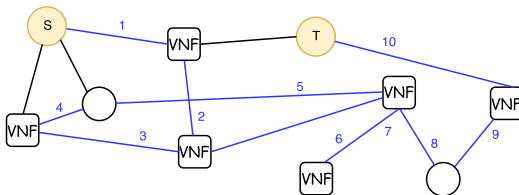
- Middlebox: Firewall, NAT, proxies, DPI etc.



A Routing Problem

moving to clouds

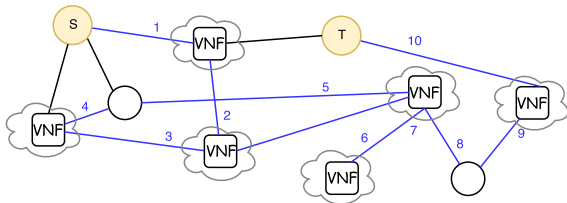
- VNFs brings flexibility, are cheaper



A Routing Problem

moving to clouds

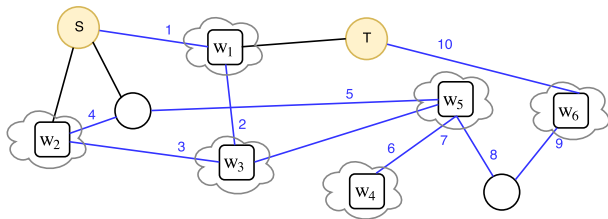
- VNFs brings flexibility, are cheaper
- A lot of them, in clouds



A Routing Problem

the waypoints

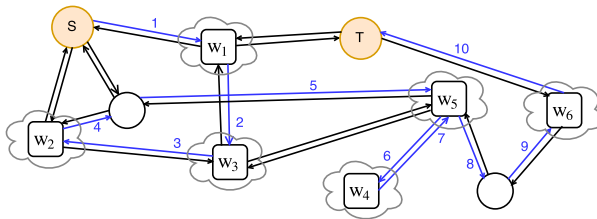
- The task: find the shortest $S-T$ walk through *waypoints*
- Capacities must be respected



A Routing Problem

the network

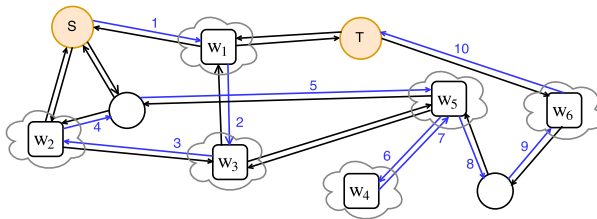
- Real Networks Are Bidirected



A Routing Problem

in two flavors

- Real Networks Are Bidirected
- Two Flavors: Ordered vs Unordered



Outline

- 1 Motivation
- 2 Model**
- 3 Warm up
- 4 Hardness
- 5 Another Variant

Model

- Bidirected graph $G(V, E)$: $\forall(x, y) \in E \implies (y, x) \in E$
- n nodes, k of which are waypoints
- Arbitrary capacities, unit demand for (S, T)

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- Arbitrary capacities, unit demand for (S, T)
- The shortest *feasible* S - T walk visiting *all* waypoints
- A feasible walk respects link capacities

Model

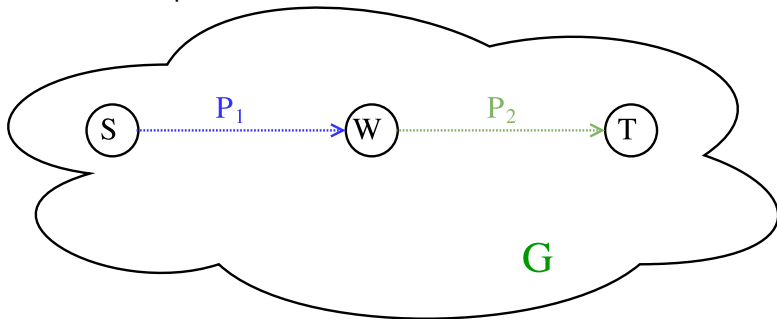
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- Ordered and Unordered

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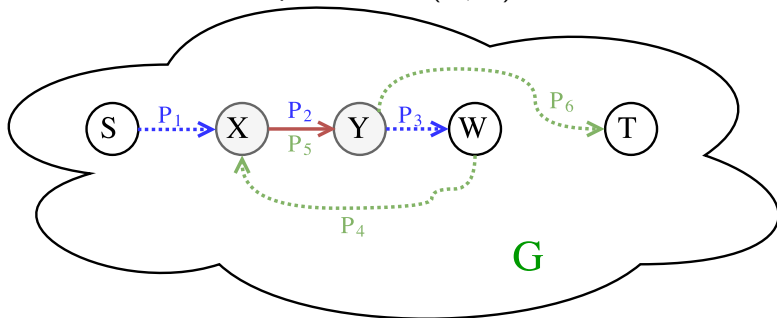
One waypoint: greedy is optimal

Two shortest paths?



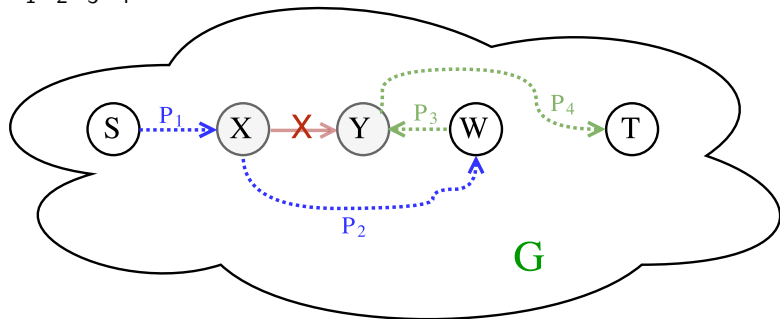
One waypoint: greedy is optimal

Assume both shortest paths chose (X, Y)



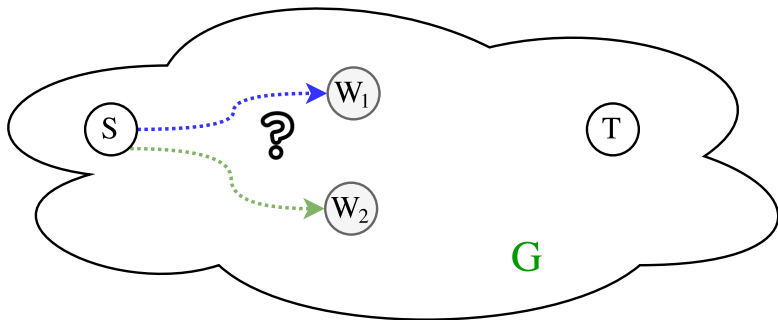
One waypoint: greedy is optimal

$P_1P_2P_3P_4$ is shorter \implies Contradiction!



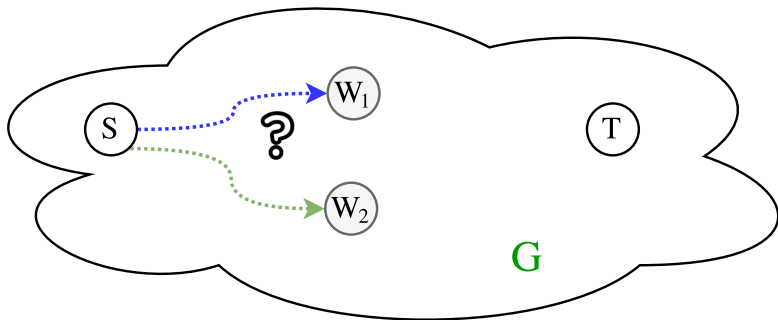
More waypoints

- ✓ The optimal order + shortest paths \implies it works!



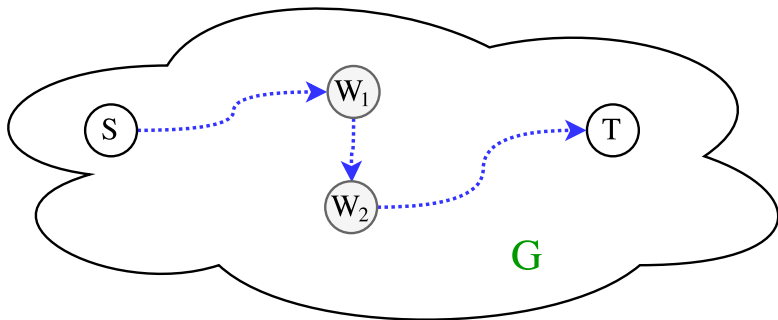
More waypoints

- ✓ The optimal order + shortest paths \implies it works!
- ✓ Try all permutations: SW_1W_2T or SW_2W_1T ?



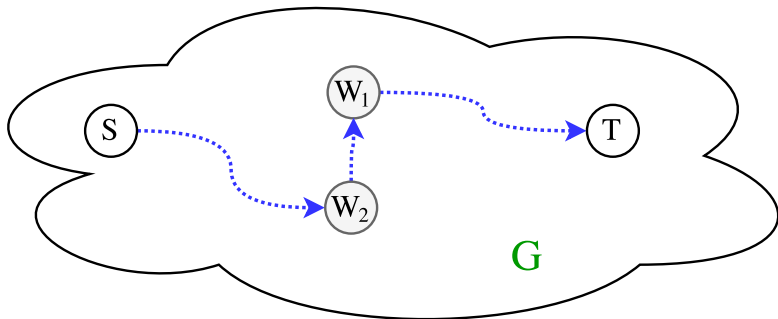
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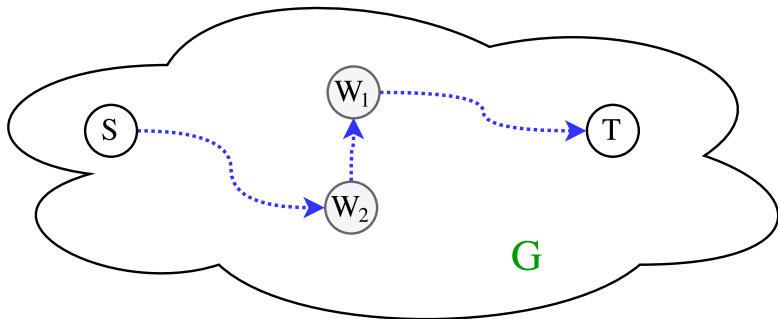
More waypoints

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More waypoints

- ✓ The optimal order + shortest paths \implies it works!
- ✓ Try all permutations: SW_1W_2T or SW_2W_1T ?
- ✓ Polynomial time for $k = \mathcal{O}\left(\frac{\log n}{\log \log n}\right)$



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Hardness

- Feasibility via spanning tree \implies always feasible

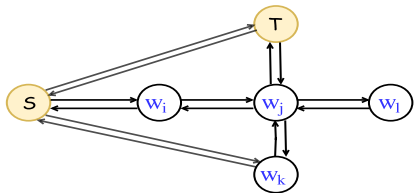


Figure: Bidirected

Hardness

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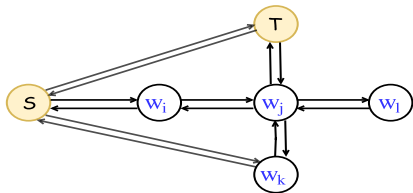


Figure: Bidirected

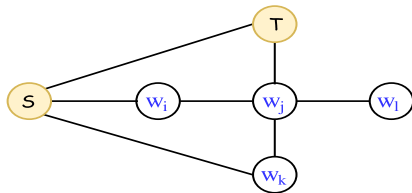


Figure: Undirected

Hardness

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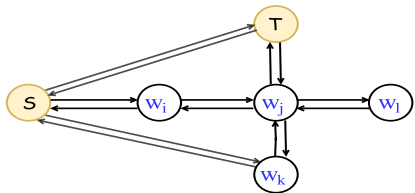


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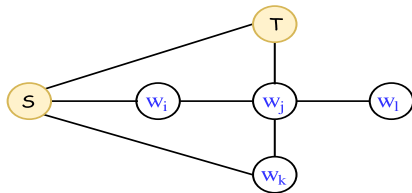


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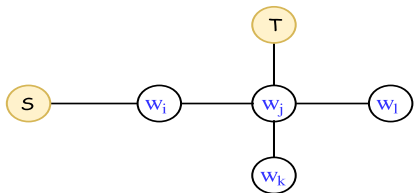


Figure: Spanning Tree

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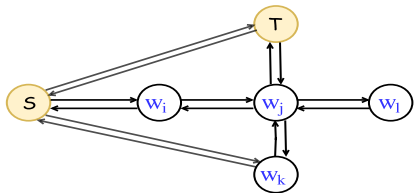


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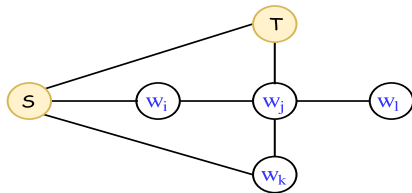


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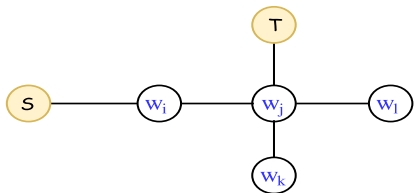


Figure: Spanning Tree

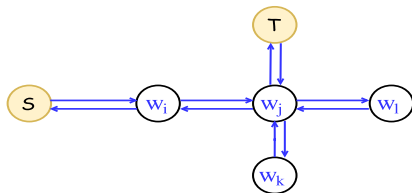


Figure: Bidirected again

Hardness

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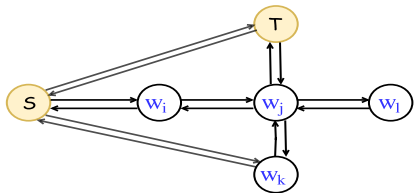


Figure: Bidirected

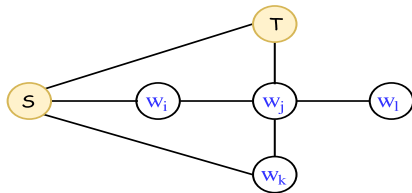


Figure: Undirected

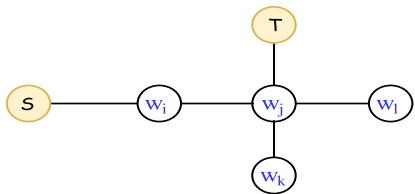


Figure: Spanning Tree

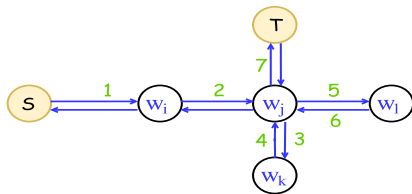


Figure: S-T tour

Hardness

- Feasibility via spanning tree \implies always feasible
- Approximation via metric TSP \implies L: $\approx 1.008^1$, U: $\approx 1.53^2$

¹Karpinski et al. J. Comput. Syst. Sci., 2015

²Andreas Seb o and Anke van Zuylen, FOCS 2016

Hardness

- Feasibility via spanning tree \implies always feasible
- Approximation via metric TSP \implies L: $\approx 1.008^1$, U: $\approx 1.53^2$
- FPT via subset TSP $\implies 2^k \cdot n^{\mathcal{O}(1)}$ (Klein and Marx, 2014)

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Ordered waypoint routing

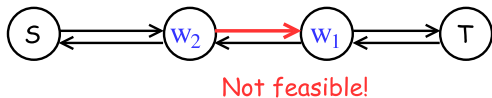
The problem

- A permutation is given, e.g. $w_1 w_2 \dots w_k$
- Find the shortest route visiting every w_i , satisfying the permutation

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- Related to **Edge Disjoint Path Problem**

Ordered waypoint routing

The problem

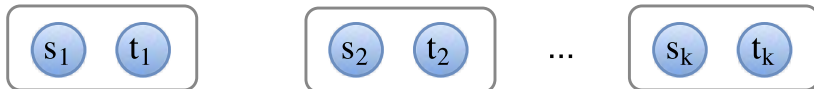
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- Find the shortest route visiting every w_i , satisfying the permutation
- Not always feasible
- Related to **Edge Disjoint Path Problem**
- NP-Hardness and feasibility via EDPP

Edge Disjoint Path Problem

EDPP

Edge Disjoint Path Problem \in NP-Complete

Find a set of pairwise edge-disjoint paths connecting every pair $(s_i, t_i), i = 1 \dots k$



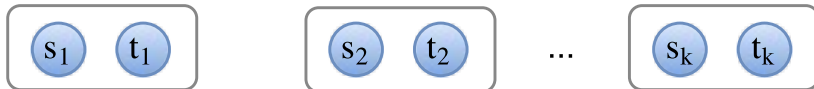
Reduction

from EDPP

Building the OWRP instance

The waypoints:

$s_1, t_1 \dots s_i, t_i, s_{i+1}, t_{i+1} \dots s_k, t_k$



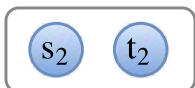
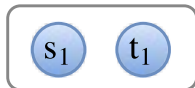
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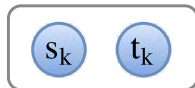
Building the OWRP instance

The waypoints:

$$S = s_1, t_1 \dots s_i, t_i, s_{i+1}, t_{i+1} \dots s_k, t_k = T$$



...



Reduction

from EDPP

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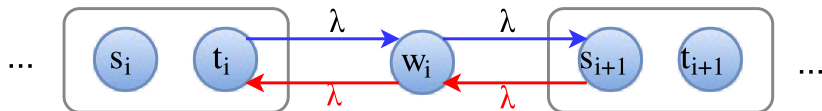
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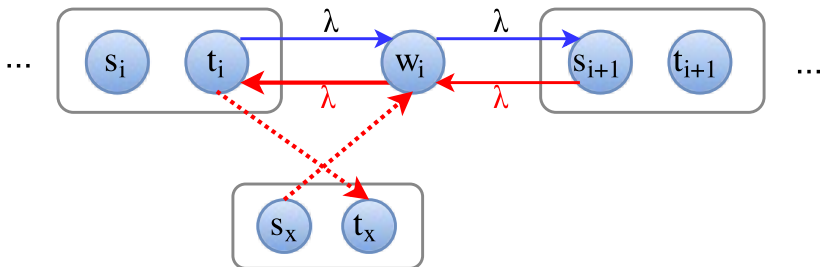
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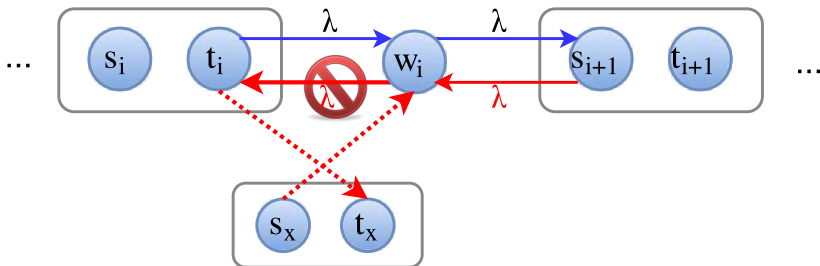
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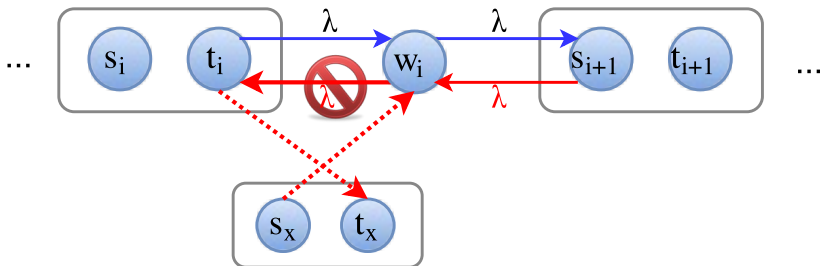
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- Set λ large enough

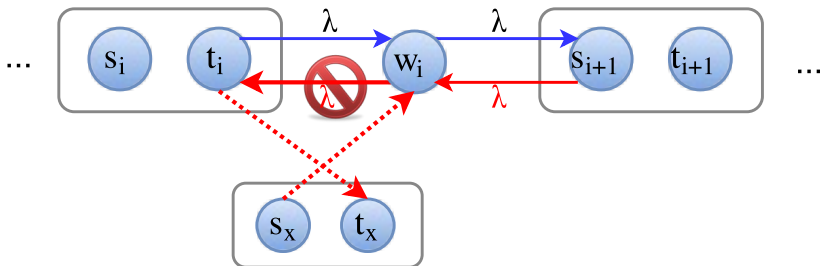
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The waypoints:

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- Set λ large enough
- OWRP chooses a backward edge \iff EDPP is not feasible

Ordered waypoint routing

Results

- General graphs: $k \in \mathcal{O}(1) \implies \text{feasibility} \in \text{P}$, via EDPP (A. Jarry et al., 2009)

Ordered waypoint routing

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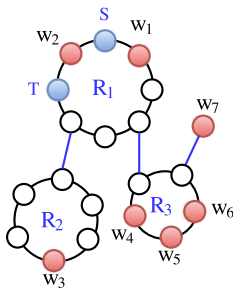
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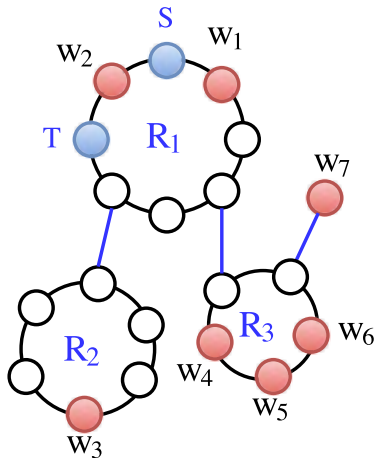
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- *Cactus graph*: tree of rings



Ordered waypoint routing

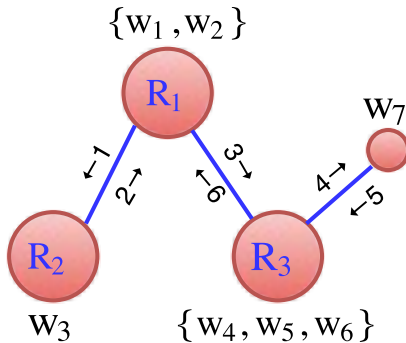
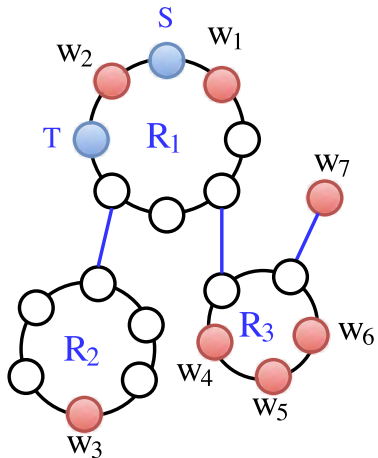
Cactus: a tree of rings



Step 1: solve the tree contraction given
 $(S = R_1), R_2, R_3, W_7, (R_1 = T)$

Ordered waypoint routing

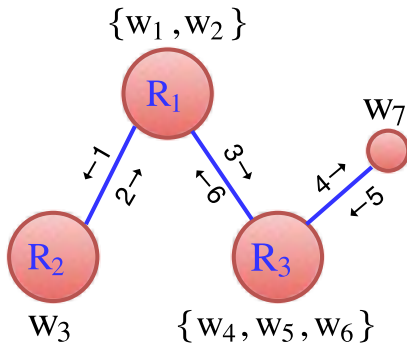
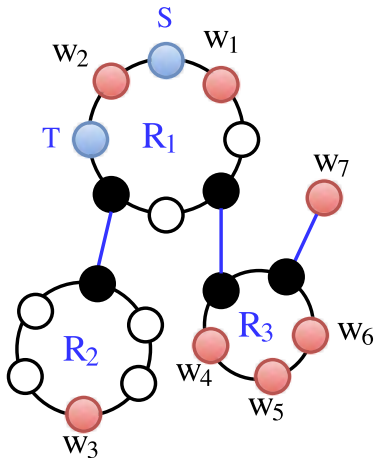
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Ordered waypoint routing

Cactus: a tree of rings



- Step 2: mark the port nodes (shown in back) as new waypoints

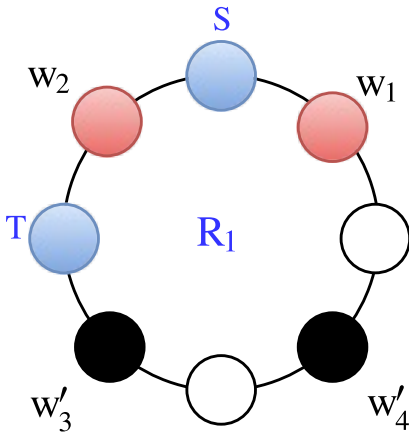
Ordered waypoint routing

Cactus: a tree of rings

- Step 2: mark the port nodes (shown in back) as new waypoints
- Step 3: solve OWRP on each ring separately

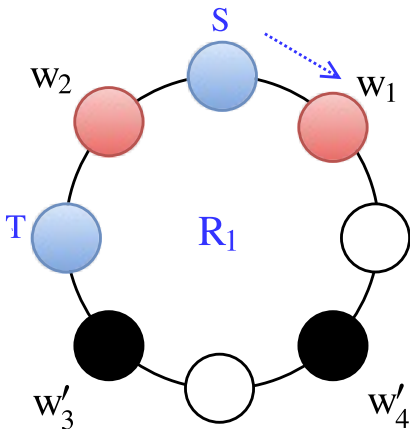
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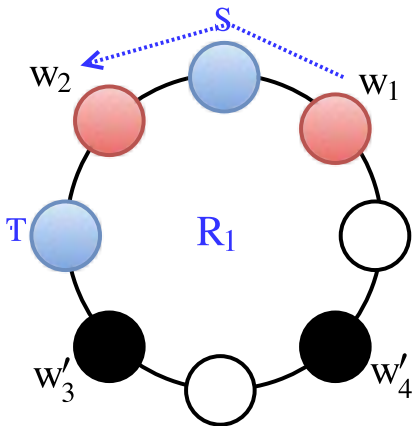
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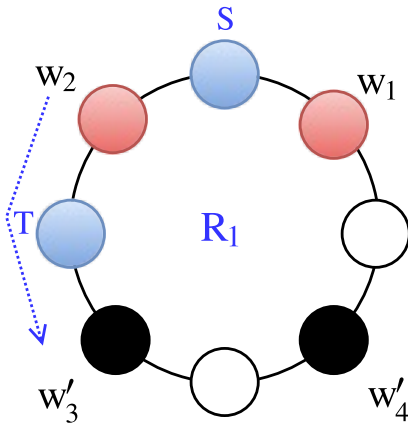
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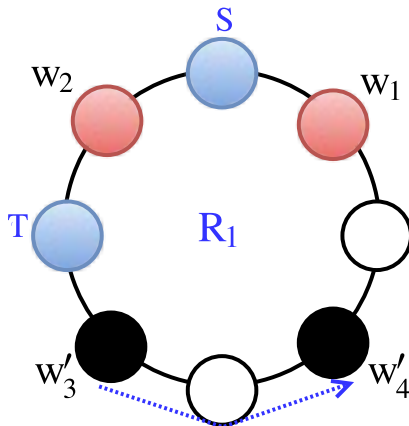
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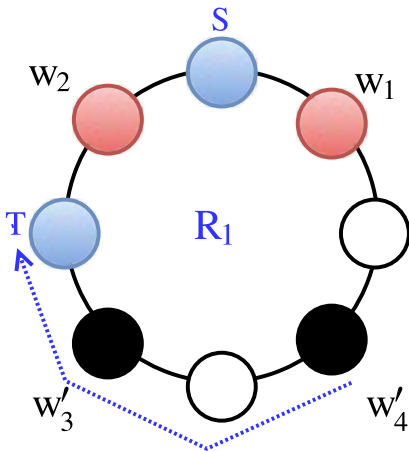
Ordered waypoint routing

Cactus: a tree of rings



Ordered waypoint routing

Cactus: a tree of rings



Summary

Table: Ordered WRP

	General	$k \in \mathcal{O}(1)$	Tree	$c_e \in \mathcal{O}(1)$
Feasibility	open	P	P	Ring \in P
Optimality	NP-Hard	open		

Table: Unordered WRP

	General	$k \in \mathcal{O}\left(\frac{\log n}{\log \log n}\right)$
Feasibility	P	
Optimality	NPH, APX, FPT	P

Open Questions

- Other special graph classes, e.g.: bidirected planar graphs
- Feasibility hardness for the ordered variant (we gave the optimality hardness)