Disconnected cooperation in resilient networks and the algorithmic challenges of local fast re-routing Stefan Schmid

Communication Networks

Critical infrastructure of digital society

- Popularity of datacentric applications: health, business, entertainment, social networking, AI/ML, etc.
- Evident during ongoing pandemic: online learning, online conferences, etc.
- Much traffic especially to, from, and inside datacenters



Facebook datacenter

Increasingly stringent dependability requirements!

Roadmap

- A Brief Background on Resilient Networking
- Algorithms for Local Fast Re-Routing (FRR)
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Traditional Networks



Software-Defined Networks (SDN)



Software-Defined Networks (SDN)



Restoration in control plane takes time -> packet drops!



Failover: Control Plane vs Data Plane

• Slower reaction in the **control plane** than in the **data plane**

VS



Minister of Education



Teacher in the Classroom

Approaches for Failover

In Control Plane

- Distributed recomputation of shortest paths ("reconvergence")
- Centralized recomputation of paths (SDN)
- Link-reversal algorithms (e.g., Gafni et al.)

VS

In Data Plane

- Static forwarding table
- Rules pre-installed *before* failures are known

Approaches for Failover











- Pre-installed local-fast failover rules
 - Can depend on local failures and, e.g., destination, inport, source
- At runtime, rules are just "executed"



Good alternative under 1 failure!

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Can get complex under multiple failures..

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With global knowledge: simpler!

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What information is **locally** available in a switch for handling a packet?



Locally Available Information: The Forwarding Table: Match -> Action



Locally Available Information: The Packet Header



Locally Available Information: The Inport of the Received Packet



Locally Available Information: The Outgoing Port Depends on Failed Links



Raises an Interesting Question

Can we pre-install local fast failover rules which ensure reachability under multiple failures? *In particular: How many failures* can be tolerated by static forwarding tables?

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So: How many failures can be tolerated by static forwarding tables?



If we partition the network, there is not much to do



The connectivity k of a network N: the minimum number of link deletions that partitions N



Resilience Criteria

Ideal resilience

Given a *k*-connected graphs, we can tolerate *any k-1 link failures*.

Perfect resilience

Any source *s* can always reach any destination *t* as long as the unterlying network is *physically connected*.

Can this be achieved? Assume undirected link failures.

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Spectrum of Models

Recall our switch model:



Achievable resilience depnds on *what can be matched*:

Per- destination	Per source	Incoming port	Probabilistic forwarding	Packet header rewriting
destination	Per source	port	forwarding	neader rewriting

Credits: Marco Chiesa

Spectrum of Models



Per-destination routing *cannot cope* with *even one* link failure



Can we achieve k – 1 resiliency in k-connected graph here?

Per- destination	Per source	Incoming port	Probabilistic forwarding	Packet header rewriting	Resiliency
Х	Х	Х			?


Can we achieve k – 1 resiliency in k-connected graph here?

Per- destination	Per source	Incoming port	Probabilistic forwarding	Packet header rewriting	Resiliency
Х	Х	Х			Yes



k disjoint paths: try one after the other, routing *back to source* each time.

Can we achieve k – 1 resiliency in k-connected graph here?

Per- destination	Per source	Incoming port	Probabilistic forwarding	Packet header rewriting	Resiliency
Х		Х			?

What about this scenario? Practically important. From now on called "ideal resilience".

Ideal Resilience: Example 2-dim Torus?







Decompose torus into 2edge-disjoint Hamilton Cycles (HC)

1st Hamilton cycle



Decompose torus into 2edge-disjoint Hamilton Cycles (HC)

1st Hamilton cycle2nd Hamilton cycle



- Decompose torus into 2edge-disjoint Hamilton Cycles (HC)
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3-resilient routing to destination d:

- go along 1st directed HC, if hit failure, reverse direction
- if again failure switch to 2nd HC, if again failure reverse direction
- No more failures possible!

Ideal Resilience with Hamilton Cycles

Chiesa et al.: if k-connected graph has k arc disjoint Hamilton Cycles, k-1 resilient routing can be constructed!

What about graphs which cannot be decomposed into Hamilton cycles?

Chiesa et al. **On the Resiliency of Static Forwarding Tables.** IEEE/ACM Transactions on Networking (ToN), 2017.

Ideal Resilience in General k-Connected Graphs

- Use directed trees (i.e. *arborescences*) instead of Hamilton cycles
 - Arc-disjoint, spanning, and rooted at destination
- Classic result: k-connectivity guarantees karborescence decomposition

Basic idea:

- Idea: route towards root on one arborescence
- After failure: change arborescence (e.g. in circular fashion)
- Incoming port defines current arborescence
- After k-1 failures: At least one arborescence intact



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J. Edmonds, **Edge-disjoint branchings**. Combinatorial Algorithms, 1972.







Credits: Marco Chiesa







General technique: routing along the same tree



When a failed link is hit...



... how do we choose the next arborescence?



But how do we choose the next arborescence?

Circular-arborescence routing:

- compute an order of the arborescences
- switch to the next arborescence when hitting a failed link

Arborescence order





Intuition: each single failure may affect two arborescences

Arborescence order



Go along arborescence 1 to destination...



Intuition: each single failure may affect two arborescences

Arborescence order



Go along arborescence 2 to destination...



Intuition: each single failure may affect two arborescences

Arborescence order



Go along arborescence 3 to destination...



Intuition: each single failure may affect two arborescences

Arborescence order



Go along arborescence 4 to destination...



Intuition: each single failure may affect two arborescences

Arborescence order





Intuition: each single failure may affect two arborescences

All k=4 arborescences used (2 failures disconnected affected all four): LOOP!

An Alternative Algorithm: Bouncing Arborescence

Bouncing-arborescence algorithm:

• Reroute on the tree that shares the failed link

This algorithm is *1-resilient*.

Bouncing-Arborescence is 1-Resilient

Start with red...

Bouncing-Arborescence is 1-Resilient



... bounce to yellow...

Bouncing-Arborescence is 1-Resilient



... bounce to red (again!)...

- Define well-bouncing arc:
 - When bounce get to the destination
 - Without hitting any other failures



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- Define **good arborescence**:
 - every failed arc is well-bouncing

1	d	
1	2	
	3	

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 - (3,1) is not well-bouncing
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- Define **good arborescence**:
 - every failed arc is well-bouncing
 - Red is not a good arborescence

1	d	
1	2	
	3	
4		
Idea: Bounce on "Good Arborescences"

- Define well-bouncing arc:
 - When bounce get to the destination
 - Without hitting any other failures
 - (3,1) is not well-bouncing
 - (1,3) is well-bouncing
- Define good arborescence:
 - every failed arc is well-bouncing
 - Red is not a good arborescence
 - Blue is a good arboresence



Ideas

- One can show that there is always a good arborescence
- An tempting idea:
 - route on an arborescence X until a failed link is hit:
 - if X is a good arborescence, bounce!
 - otherwise, route circular
- Too good to be true:
 - The "goodness" of an arborescence depends on the actual set of failed links!
 - How do we know a arborescence is good?

Resilience Criteria

Ideal resilience

Given a *k*-connected graphs, we can tolerate *any k-1 link failures*.



Any source *s* can always reach any destination *t* as long as the unterlying network is *physically connected*.

Can this be achieved? Assume undirected link failures.

Resilience Criteria

Perfect resilience is impossible to achieve in general.

Relevant Neighbors

- Routing table of node *i*: matches in-ports of *i* to out-ports of *i*
 - ... depending on the incident failures
- But not all neighbors are relevant: only if potentially required to reach destination!
 - Without local failures: just v_2, v_3 for *i*, since v_1 does not give extra connectivity



Relevant Neighbors

- Routing table of node *i*: matches in-ports of *i* to out-ports of *i*
 - ... depending on the incident failures
- But not all neighbors are relevant: only if potentially required to reach destination!
 - Without local failures: just v_2 , v_3 for *i*, since v_1 does not give extra connectivity
 - With additional failures v_1 becomes relevant, since v_1 might be only choice to reach destination t
 - Note: v_1 is unaware of these non-incident failures!



High-level definition of *relevant*: From the local view-point of the node *i*, a relevant neighbor might be only neighbor to reach destination (without taking a detour over a current neighbor).

How to Achieve Perfect Resilience?

- Necessary: need to try all relevant neighbors
 - Here, if local link to v_2 broken: v_1 and v_3
- That is, if packet
 - comes from v_3 : eventually try v_1
 - comes from v_1 : eventually try v_3



Some observations:

- Additional failures only *add relevant neighbors* to nodes
- Any node of *degree 2* of G after failures must forward packets with incoming port p to port p'
- If all neighbors are relevant, the forwarding function of a node must be a *cyclic permutation*

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Idea of the counter example:



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Proof idea, with three cases:

- If the *dashed* links fail (*non-local* to node 1), in any forwarding pattern, packets will be stuck in one of the *blue loops*...
- ... even though there is at least one remaining path to the target

Go through all possible permutations @1 and give counter example.











For node 1:	For node 1:	For node 1:
5->2 implies	5->3 implies	5->4 implies
(5,2,3,4) (b)	(5,3,4,2) (a)	(5,4,2,3) (c)
(5,2,4,3) (a)	(5,3,2,4) (c)	(5,4,3,2) (b)

Possible cyclic permutations: packet arriving on port 3 can only be forwarded to either 5 or 2. Leads to *loops* in scenarios (c) and (b), respectively.

A Pity: Planar Graphs Are Important

- Internet Topology Zoo and Rocketfuel topologies
 - 88% of the graphs are *planar*



A Pity: Planar Graphs Are Important

- Internet Topology Zoo and Rocketfuel topologies
 - 88% of the graphs are *planar*
 - However:
 - Almost a third (32%) belong to the family of *cactus* graphs
 - Roughly half of the graphs (49%) are outerplanar
 - ... and they work 🙂



Where Can Perfect Resilience Be Achieved?

For example on outerplanar graphs:

- Via *geometric routing*, well studied in sensor networks etc.
- Embed graph in the plane s.t. all nodes are on the outer face
 - Note: If a link I belongs to the outer face of a planar graph G, it also belongs to the outer face for all subgraphs of G
- Apply *right-hand rule* to forwarding (skipping failures)
 - Ensures packets use only the links of the outer face and do not change the direction despite failures
- Strategy traverses all nodes on the outer face
- Also works for any graph which is *outerplanar without the source* (e.g., K4)

Some Observations

- *K*_5, *K*_3,3: *no perfect resilience*
- Perfect resiliency on graph G -> any subgraph G' of G also allows for perfect resiliency
 - Idea: Take routing on G, fail edges to create G', routing must still work



- Contraction works as well, by a simulation argument
 - A bit technical
- Combined: Perfect resilience on graph G -> any minor G' of G as well
 - But since K_5, K_3,3 not: non-planar graphs not perfectly resilient



What we know about perfect resilience

Possible:

- On all outerplanar graphs [right-hand rule]
- On every graph that is outerplanar without the destination (e.g. non-outerplanar planar *K*_4)

Impossible:

- On some planar graphs
- Every non-planar graph
- Perfect resilience must hold on minors





Foerster et al. On the Feasibility of Perfect Resilience with Local Fast Failover. SIAM Symposium on Algorithmic Principles of Computer Systems (APOCS), 2021.

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Assume we can match source.









Failover table: flow 1->t: 2,3,4,5,...



Preinstalled failover rules for red, blue and green flows

Failover table: flow 1->t: 2,3,4,5,...



Finally, t is reached!





Failover table: flow 1->t: 2,3,4,5,...



Observation: we can represent failover tables as a matrix. To load balance: prefixes of rows should be different!





be "reused".

What Are Good Failover Matrices?

- The matrices should be Latin squares: each node appears exactly once on each row and each column. No repetitions implies loop-freedom.
- Latin squares property gives high resilience, but is not sufficient for minimizing load.

Challenging Example: Incast

Traffic demand: {1,2,3,4,5}->t 2 3 5 4

In the following, consider *all-to-one* demand pattern.

A Bad Matrix for Load

Src 1:	2	3	4	5
Src 2:	3	4	5	1
Src 3:	4	5	1	2
Src 4:	5	1	2	3
Src 5:	1	2	3	4


A Bad Matrix for Load





Failing (1,t), (2,t), (3,t), (4,t), gives load 4 on node 5 / link (5,t).

If the adversary fails the / first links to destination d (that is, {(v_i,t), i = 1, ..., /}), then / sources will route through (v_{i+1},t). Load / for / failures. Can we do better?

Good Failover Matrices?

- To bring the flow from a source i to a node X, need to fail *all links* in corresponding *row*
 - Worst case: all to destination
- The same for each other flow/row which should reach X





Good Failover Matrices?

- To bring the flow from a source i to a node X, need to fail *all links* in corresponding *row*
 - Worst case: all to destination
- The same for each other flow/row which should reach X
- Adversary will try to reuse link failures: good matrices have prefixes with little overlap (resp. large number of unique nodes)





Connection to Block Designs

- A closely related problem: generating **block designs**
 - and its geometric counterpart, generating projective planes of high order
- Using symmetric balanced incomplete block designs (BIBDs)
- Gives a latin failover matrix M with intersection properties representing a failover scheme that is *optimal up to a constant factor*
- Also used in the context **disconnected cooperation**, e.g.:
 - G. Malewicz, A. Russell, and A. A. Shvartsman. Distributed Scheduling for Disconnected Cooperation. Distributed Computing, 18(6), 2005.

Overview of Results

Good news: Theory of local algorithms without communication: symmetric block design theory.

Bad news (counting argument): High load unavoidable even in well-connected residual networks: a price of locality.
Given L failures, load at least √L, although network still highly connected (n-L connected). E.g., L=n/2, load could be 2 still, but due to locality at least √n.

Borokhovich et al. Load-Optimal Local Fast Rerouting for Dense Networks. IEEE/ACM Transactions on Networking (TON), 2018.

Randomized Failover

 Recall: deterministic lower bound of VL for L failures, although load could be O(1) for L<L/2. A large *price of locality*.

• So what about *randomized* approaches?



The Power of Randomization

	3-Permutations	Intervals	Shared-Permutations
Rule Set	Destination + Hop	Destination	Destination + Hop
Resilience	$\Theta(n)$	$\Theta(n/\log n)$	$\Theta(n)$
Congestion	$\mathcal{O}(\log^2 n \cdot \log \log n)$	$\mathcal{O}(\log n \cdot \log \log n)$	$\mathcal{O}(\sqrt{\log n})$

- While deterministic algorithms can at best achieve a *polynomial* load, randomized algorithms can achieve a *polylogarithmic load*.
- Even when just matching the destination.
 - Losing a log n factor in resilience.
 - Matching also the hop count can overcome this.

Bankhamer et al. Local Fast Rerouting withLow Congestion: A Randomized Approach.27th IEEE International Conference onNetwork Protocols (ICNP), 2019.

Benefits in Datacenter Networks



What About Path Length and Stretch?

- So far: ignored the length of the failover routes
 - Hamilton cycles are particularly bad
 - The heights of general arborescences may be lower







- Idea (so far heuristic):
 - Postprocess the arborescences to lower their heights
 - Two different t-rooted arc-disjoint spanning arborescence decompositions, T1 and T2
 - The mean path length of T1 is higher than that of T2

Foerster et al. **Improved Fast Rerouting Using Postprocessing** (Best Paper Award). 38th International Symposium on Reliable Distributed Systems (SRDS), 2019.

Swapping Operations Which Maintain Decomposition



Before swapping



After swapping





Before swapping

After swapping

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An example with header rewriting.

Case Study: MPLS Networks

- Widely deployed networks by Internet Service Providers (ISPs)
- Often used for traffic engineering
 - Avoid congestion by going non-shortest paths
- Allows for *header re-writing* upon failures
 - Header based on stack of labels

How (MPLS) Networks Work

• Forwarding based on top label of label stack



Default routing of two flows

How (MPLS) Networks Work

• Forwarding based on top label of label stack



How (MPLS) Networks Work



Default routing of two flows

Fast Reroute Around 1 Failure

• Forwarding based on top label of label stack (in packet header)



Default routing of two flows

• For failover: push and pop label



One failure: push 30: route around (v_2, v_3)

Fast Reroute Around 1 Failure

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Fast Reroute Around 1 Failure

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2 Failures: Push *Recursively*



Original Routing

One failure: push 30: route around (v_2, v_3)

Two failures: first push 30: route around (v₂,v₃) *Push recursively* 40: route around (v₂,v₆)

2 Failures: Push *Recursively*







Routers and switches store list of forwarding rules, and conditional failover rules.





Sysadmin responsible for:

• **Reachability:** Can traffic from ingress port A reach egress port B?



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k failures = ssibilities А E.g. IDS

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... and everything even under multiple failures?!



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Generalization: service chaining!

Approach: Automation and Formal Methods



Router **configurations** (Cisco, Juniper, etc.) Pushdown Automaton and Prefix Rewriting Systems



Router configurations (Cisco, Juniper, etc.) Pushdown Automaton and Prefix Rewriting Systems

Jensen et al. **P-Rex: Fast Verification of MPLS Networks with Multiple Link Failures**. 14th ACM International Conference on emerging Networking EXperiments and Technologies (CoNEXT), 2018.

AalWiNes Tool



Online demo: <u>https://demo.aalwines.cs.aau.dk/</u> Source code: <u>https://github.com/DEIS-Tools/AalWiNes</u>

Example

Can traffic starting with [] go through s5, under up to k=2 failures?



Why AalWiNes is Fast (Polytime): Automata Theory

- For fast verification, we can use the result by Büchi: the set of all reachable configurations of a pushdown automaton a is regular set
- We hence simply use Nondeterministic Finite Automata (NFAs) when reasoning about the pushdown automata



Julius Richard Büchi 1924-1984 Swiss logician

• The resulting **regular operations** are all **polynomial time**

AalWiNes


Network Model

• Network: a 7-tuple $N = (V, E, I_v^{in}, I_v^{out}, \lambda_v, L, \delta_v^F)$ Nodes

Network Model

• Network: a 7-tuple

$$N = (V, E, I_v^{in}, I_v^{out}, \lambda_v, L, \delta_v^F)$$

Interface function: maps outgoing interface to next hop node and incoming interface to previous hop node $\lambda_v: I_v^{in} \cup I_v^{out} \to V$

That is:
$$(\lambda_v(in), v) \in E$$
 and $(v, \lambda_v(out)) \in E$

Network Model

• Network: a 7-tuple

$$N = (V, E, I_v^{in}, I_v^{out}, \lambda_v, L, \delta_v^F)$$

Routing function: for each set of failed links $F \subseteq E$, the routing function

$$\delta_v^F: I_v^{in} \times L^* \to 2^{(I^{out} \times L^*)}$$

defines, for all incoming interfaces and packet headers, outgoing interfaces together with modified headers.

Routing



• Example: routing (in)finite sequence of tuples



Case Study: NORDUnet

- Regional service provider
- 24 MPLS routers geographically distributed across several countries
- Running Juniper operating system
- More than 30,000 labels
- Ca. 1 million forwarding rules in our model
- For most queries of operators: answer *within seconds*



Generalizes to Quantitative Properties

- AalWiNes can also be used to test quantitative properties
- If query is satisfied, find trace that minimizes:
 - Hops
 - Latency (based on a latency value per link)
 - Tunnels



- Approach: weighted pushdown automata
 - Fast *poly-time algorithms* exist also for weighted pushdown automata (area of dataflow analysis)
 - Indeed, experiments show: acceptable overhead of weighted (quantitative) analysis

Conclusion

- Fast rerouting requires *local decision making*
- Different fault-tolerance *metrics*: ideal resilience, perfect resilience
- What can be achieved depends on *what can be matched* locally
- Locally *balancing load* under failures is hard, but randomization helps

What About The Control Plane?

Still many open questions too, see e.g., *TACAS 2021*

Resilient Capacity-Aware Routing

Stefan Schmid¹, Nicolas Schnepf², and Jiří Srba²

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 ² Department of Computer Science, Aalborg University

Abstract. To ensure a high availability, most modern communication networks provide resilient routing mechanisms that quickly change routes upon failures. However, a fundamental algorithmic question underlying such mechanisms is hardly understood: how to efficiently verify whether a given network reroutes flows along *feasible* paths, without violating capacity constraints, for up to k link failures? We chart the algorithmic complexity landscape of resilient routing under link failures, considering shortest path routing based on link weights (e.g., the widely deployed ECMP protocol). We study two models: a *pessimistic* model where flows interfere in a worst-case manner along equal-cost shortest paths, and an optimistic model where flows are routed in a best-case manner and we present a complete picture of the algorithmic complexities for these models. We further propose a strategic search algorithm that checks only the critical failure scenarios while still providing correctness guarantees. Our experimental evaluation on a large benchmark of Internet and datacenter topologies confirms an improved performance of our strategic search algorithm by several orders of magnitude.

What About Segment Routing?



See e.g., *GI 2018* and *OPODIS 2020*

Maximally Resilient Replacement Paths for a Family of Product Graphs 3 Mahmoud Parham 💿 University of Vienna, Faculty of Computer Science, Vienna, Austria mahmoud.parham@univie.ac.at Klaus-Tycho Foerster 💿 University of Vienna, Faculty of Computer Science, Vienna, Austria klaus-tycho.foerster@univie.ac.at ¹⁰ University of Vienna, Faculty of Computer Science, Vienna, Austria 11 petar.kosic@univie.ac.at 12 Stefan Schmid 💿 University of Vienna, Faculty of Computer Science, Vienna, Austria 13 stefan_schmid@univie.ac.at 14 ¹⁶ Modern communication networks support fast path restoration mechanisms which allow to reroute traffic in case of (possibly multiple) link failures, in a completely decentralized manner and without requiring global route reconvergence. However, devising resilient path restoration algorithms is challenging as these algorithms need to be inherently local. Furthermore, the resulting failover paths 17 often have to fulfill additional requirements related to the policy and function implemented by the 18 network, such as the traversal of certain waypoints (e.g., a firewall). This paper presents local algorithms which ensure a maximally resilient path restoration for a 20 large family of product graphs, including the widely used tori and generalized hypercube topologies. 21 Our algorithms provably ensure that even under multiple link failures, traffic is rerouted to the other 22 endnoint of every failed link whenever nossible (i.e. detouring failed links) enforcing wavnoints and 23 24

What About Segment Routing?





What About Segment Routing?

- We need two definitions:
 - P-Space: the nodes whose shortest path from S does not use L
 - Q-Space: the nodes whose shortest path to T does not use L



Idea: choose segment endpoint w at intersection!

Two Cases

P-Space and Q-Space: Are **connected** subgraphs, **cover** all nodes, **overlap** or are **adjacent**



TI-LFA Under Double Failure



TI-MFA Under Double Failure



TI-MFA Under Double Failure



From the viewpoint of the node S where the packet hits another failed link:

- 1. Flush the label stack except for the destination T
- 2. Based on all link failure info stored in the packet header, compute the segments necessary to reach *T* and the labels accordingly
- 3. Find the last node on *ShortestPath(S,T)* that a packet can reach from *S* without hitting known failed link ("repeated TI-LFA on subgraph")
 - a. Let V1 be this node followed by the link (V1,V2) on this path
 - b. Set the top of label stack as (V1, (V1,V2),...
 - c. Repeat the same for V2 as the start of next segment and keep repeating until the segment that ends with T
- 4. Dispatch the packet (it will reach T unless it hits a failure disconnecting the network)

Theorem: TI-MFA tolerates k failures in k-connected network!

Proof:

- Invariant: by construction, previously hit failures won't be hit again
- *k* failures: by construction the backup path will not use any failed link seen previously
- Hence, the packet either hits all the k failures or reaches its destination early

Efficient Implementation of FRR?

PURR: A Primitive for Reconfigurable Fast Reroute

(hope for the best and program for the worst)

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> Georgios Nikolaidis Barefoot Networks

See e.g., *CoNEXT 2019*

ABSTRACT

Highly dependable communication networks usually rely on some kind of Fast Re-Route (FRR) mechanism which allows to quickly re-route traffic upon failures, entirely in the data plane. This paper studies the design of FRR mechanisms for emerging reconfigurable switches.

Our main contribution is an FRR primitive for *programmable* data planes, PURR, which provides low failover latency and high switch throughput, by *avoiding packet recirculation*. PURR tolerates multiple concurrent failures and comes with minimal memory requirements, ensuring *compact* forwarding tables, by unveiling an intriguing connection to classic "string theory" (*i.e.*, stringology), and in particular, the shortest common supersequence problem. PURR is well-suited for high-speed match-action forwarding architectures (e.g., PISA) and supports the implementation of aritrary network-wide FRR mechanisms. Our simulations and prototype implementation (on an FPGA and Tofino) show that PURR improves

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1 INTRODUCTION

Emerging applications, e.g., in the context of business [21] and entertainment [57], pose stringent requirements on the dependability and performance of the underlying communication networks, which have become a critical infrastructure of our digital society. In order to meet such requirements, many communication networks provide *Fast Re-Route* (FRR) mechanisms [5, 39, 64] which allow to quickly reroute traffic upon unexpected failures, entirely in the <u>A Survey of Fast-Recovery Mechanisms in Packet-Switched Networks</u> Marco Chiesa, Andrzej Kamisinski, Jacek Rak, Gabor Retvari, and Stefan Schmid. IEEE Communications Surveys and Tutorials (**COMST**), 2021.

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Questions?

Backup Slides

Remark: Traditional Approach LFA

- Traditionally: forwarding along shortest paths
- Loop-Free Alternative (LFA): failover to alternative neighbor, from there shortest path

Example 1:

- If (s,v) fails, s can failover to u
- *u* has shortest path to *t* that does not go through (*s*,*v*) again
- WORKS: can protect (s,v)



Remark: Traditional Approach LFA

- Traditionally: forwarding along shortest paths
- Loop-Free Alternative (LFA): failover to alternative neighbor, from there shortest path

Example 2:

- If (*s*,*t*) fails, *s* can only try to failover to *v*
- However, when v's shortest route to t goes along s again: loop
- DOES NOT WORK: Cannot protect (s,t)



Remark: Traditional Approach LFA

- Traditionally: forwarding along shortest paths
- Loop-Free Alternative (LFA): failover to alternative neighbor, from there shortest path

Example 2:

- If (*s*,*t*) fails, *s* can only try to failover to *v*
- However, when v's shortest route to t goes along s again: loop
- DOES NOT WORK: Cannot protect (s,t)

Even though loop-free alternative path exists, an LFA algorithm cannot use it. Protection ratio of LFA depends on topology.

