On the power of preprocessing in decentralized network optimisation

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Everybody's favourite network topology, the ring



Problem: 2-coloring

Locality: 2-coloring



Each computer must decide its own color

Locality: 2-coloring



Each computer must decide its own color



Once a color is fixed, it is propagated

Locality: 3-coloring



What if we have one extra color?

Locality

- 2-coloring a ring is inherently *global*: each node must see the whole network in order to decide its color
- 3-coloring a ring is inherently *local:* a greedy approach works, nodes need only to avoid the colors of their neighbors

We want to understand the **locality** of problems

This talk

Theory warning!

- 1. Modelling the concept of **locality**
- 2. Recent developments in theoretical understanding
- 3. Transferring the understanding to the context of networking (e.g. *distributed SDN control plane*)



Modelling and undestanding locality

Modeling locality

- LOCAL model of Linial (SICOMP, 1992)
- Model locality by *abstracting away* other aspects of distributed computing
 - Synchronous communication rounds
 - Unbounded messages
 - Free of faults, crashes, byzantine behavior
 - Static network, no dynamic changes



- In T synchronous rounds flooding collects all information inside T-hop neighbourhood
 - In particular, no information outside the T-hops!

time = distance



Complexity

= number of communication rounds (time)= radius of each node's view (distance)

time = distance

Locality of some problems

- Classic symmetry breaking problems are *local*: MIS, MM, (Δ+1)-coloring in O(Δ + log* n) rounds*
- 2-coloring, MST, spanners, leader election are *global*, require diameter time
- optimization, new "intermediate" problems in polylog in n time
- everything in diameter time

 Δ = maximum degree log* (number of atoms in the observable universe) = 5

Algorithmic model?

Asynchronous: use synchronisers

Limited bandwidth: algorithms often don't abuse this (e.g. *coloring, network decomposition* with O(log n)-bit messages)

Fault-tolerance: efficient distributed algorithms stabilise quickly after faults, dynamic changes

However, e.g. triangle detection trivial in LOCAL

Impossibility results

- **Powerful model** implies very general **negative results**
 - Results apply in the presence of congestion, faults, asynchrony, byzantine behaviour, ...
- Upper bounds show whether tasks are locality constrained

Impossibility results

- **Powerful model** implies very general **negative results**
- A number of *recent developments*
 - Simulation speedup for intermediate problems (Brandt et al., STOC 2016)
 - Simulation gap and derandomization (Chang et al., FOCS 2016)
 - SLOCAL-completeness (Ghaffari et al., STOC 2017)
 - Derandomization (Ghaffari et al., FOCS 2018)
 - Simulation speedup for maximal matching (Balliu et al., 2019)

Locally checkable labellings



Locality, networking, preprocessing

Modelling locality in networking

- We study a particular model, the supported LOCAL model of Schmid and Suomela (HotSDN, 2013)
- Inspiration e.g. a distributed control plane in SDN
 - The physical network known in advance
 - The global logical state of the network unknown
- Also a study on the **power of preprocessing**

Supported LOCAL



support = graph **known** to all nodes

Supported LOCAL



network, logical graph = **subgraph** of the support

Supported LOCAL

- At least as powerful as the LOCAL model
 - The input is a subgraph of the globally and consistently known support
- Are the "removed" edges available for communication?
 - Affects computational power
 - active / passive model

The Bad, The Good

- Support is not useful in some corner cases
- Let's make a wild assumption: we have some degree of control over the network...
 - We can actually **design** the network?
 - The switches have a **finite** number of ports?

Our work

- The support can be used to precompute various useful primitives, e.g.
 - coloring
 - network decomposition
 - spanning tree
- Support particularly useful if it has nice structure

Coloring

- In networks of e.g. bounded maximum degree, colorings are a useful primitive
- many problems solvable in constant time given a coloring (i.e. independent of the network size)

Coloring



Coloring



Colorings

- Coloring \rightarrow greedy algorithms (e.g. maximal matching, maximal independent set, (Δ +1)-coloring)
- Distance-T coloring → simulate and speed up LOCAL
- **Distance-T coloring** → simulate **SLOCAL**

Special graph classes

- Support with small chromatic number is useful
- Planar graphs are particularly useful (4-colorable, large degree)
 - Case study: approximation of minimum dominating set
 - Use preprocessing to speed up subroutines in existing distributed algorithms
 - (1+ε)-approximation in constant time

Network decomposition



Network decomposition

- Useful primitive in the case of large degrees (coloring a special case!)
- All edges must be available for communication to be useful (removing edges affects cluster diameter)
- Simulation of the SLOCAL model of Ghaffari et al. (STOC 2016)
 - PSLOCAL-completeness: supported LOCAL closes the gap between randomised and deterministic
 - Symmetry breaking in **polylog time**

Impossibility in the supported LOCAL

• Example: Hardness of approximation for maximum cut

- 2 vertex labels, edge is *cut*, if endpoints have different labels
- optimum cannot be found in o(log n) rounds
- hard even in the active model with bounded degrees



 Proof sketch: "hide" subgraphs with large and small optima in the support s.t. locally you cannot know which one has been selected

Concluding

- Understanding of locality in distributed message passing has developed significantly in recent years
- This understanding can be extended to models of networking
 - Lot of work still left!
- Network topology can be designed to improve the locality of distributed algorithms