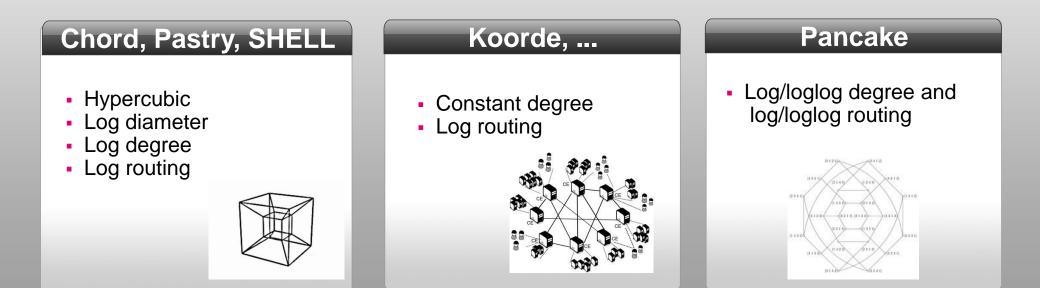
#### OBST: A Self-Adjusting Peer-to-Peer Overlay Based on Multiple BSTs

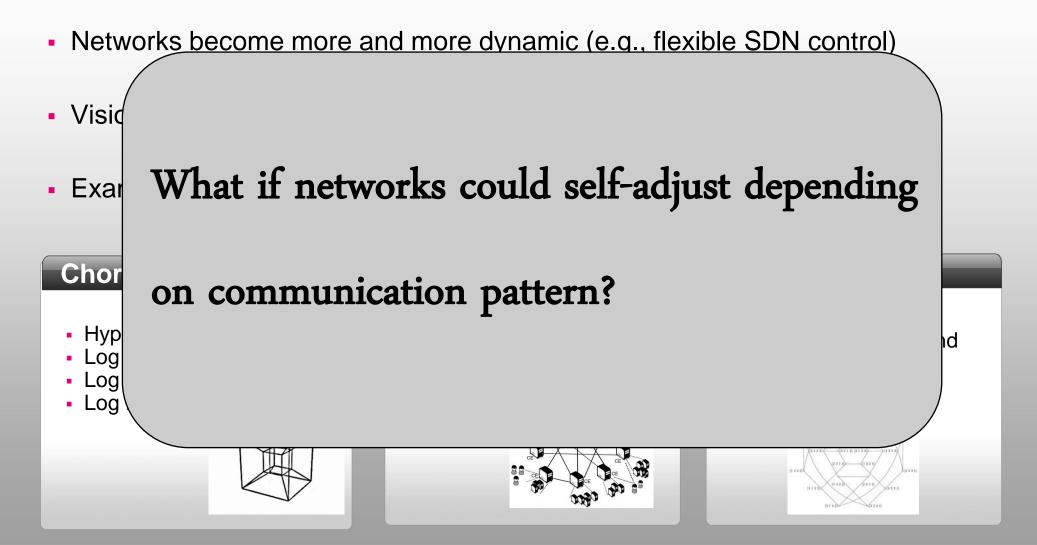
Chen Avin (BGU) Michael Borokhovich (BGU) Stefan Schmid (T-Labs)

## From "Optimal" Networks to Self-Adjusting Networks

- Networks become more and more dynamic (e.g., flexible SDN control)
- Vision: go beyond classic "optimal" static networks
- Example (of this paper): Peer-to-peer

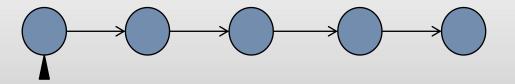


## From "Optimal" Networks to Self-Adjusting Networks

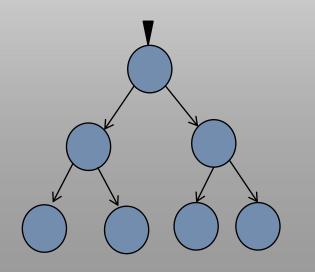


## An Old Concept: Move-to-front, Splay Trees, ...

- Classic data structures: lists, trees
- Linked list: move frequently accessed elements to front!

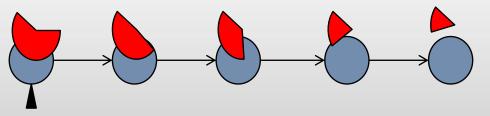


Trees: move frequently accessed elements closer to root

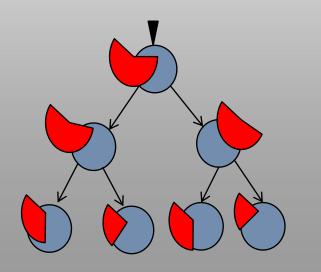


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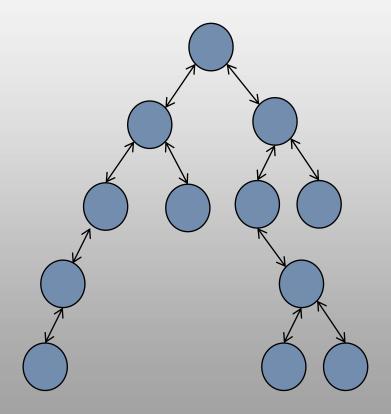


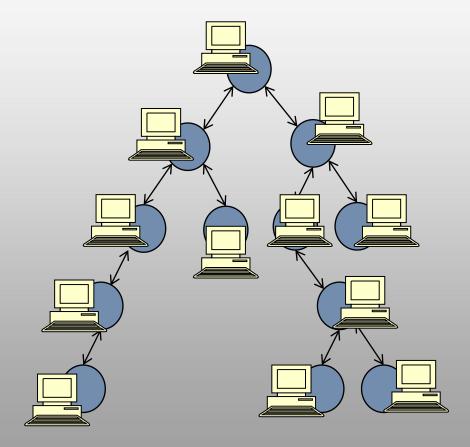
## An Old Concept: Move-to-front, Splay Trees, ...

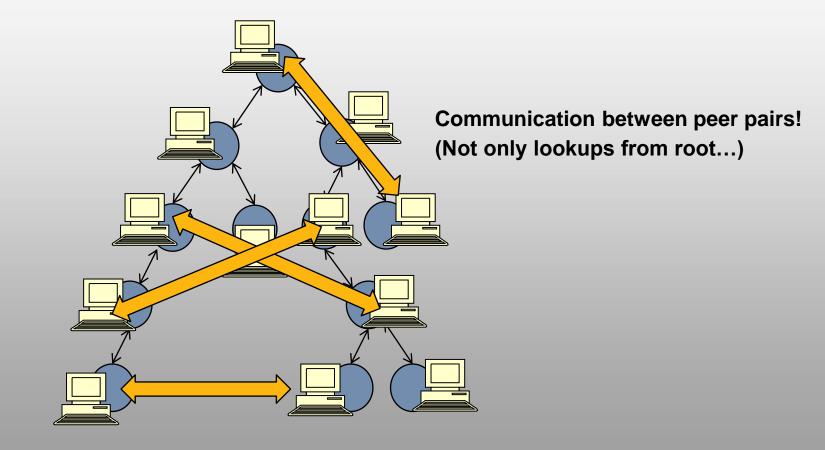
- Classic data structures: lists, trees •
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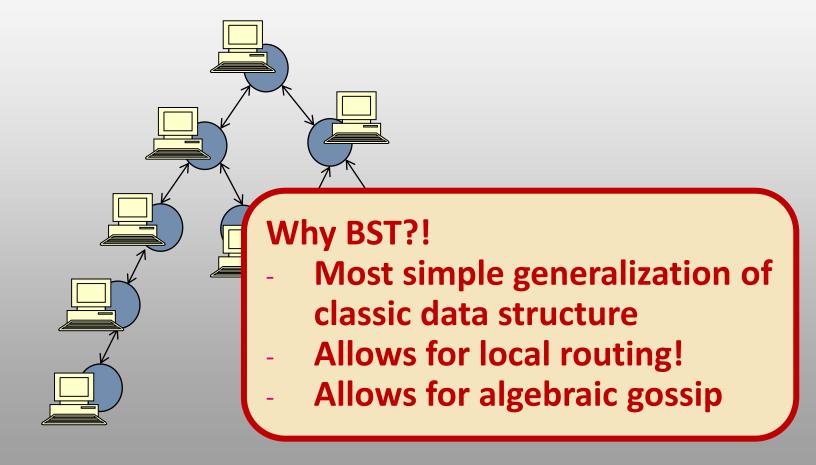
Trees: move frequently accessed elements











# Model: Self-Adjusting SplayNets

#### Input:

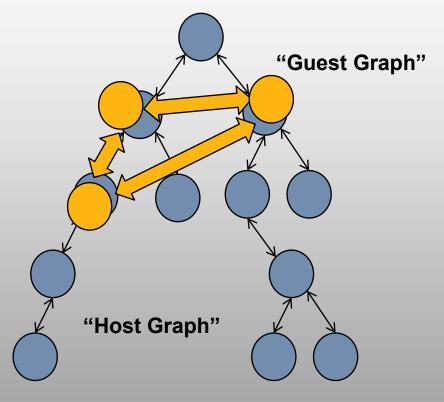
 communication pattern: (static or dynamic) graph

#### Output:

sequence of network adjustments

#### Cost metric:

- expected path length
- # (local) network updates



### Some Facts: Optimal Algorithm and Amortized Cost

#### **Optimal Static Solution**

- Dynamic program: decouple left from right!
- Polynomial time (unlike MLA!)
- So: solved M"BST"A

## **Upper Bound**

#### A-Cost < H(X) + H(Y)

where H(X) and H(Y) are empirical entropies of sources resp. destinations

Adaption of Tarjan&Sleator

#### **Dynamic Solution**

- There exists self-adjusting algorithm
- Inspired by Splay trees
- E.g., optimal under product distribution: P[(u,v)]=P(u)\*P(v)
- E.g., optimal under directed BST, noncrossing matching, ...
- Lower bounds…

#### **Lower Bound**

#### A-Cost > H(X|Y) + H(Y|X)

where H( | ) are conditional entropies.

Assuming that each node is the root for "its tree"

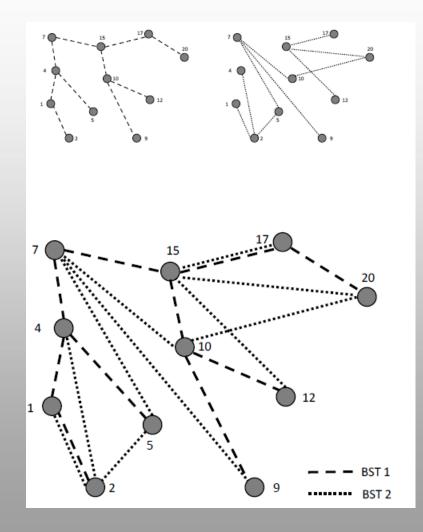
## From One to Multiple BSTs

#### **Research Question:**

- What is the benefit of multiple BSTs?
- Focus on amortized communication cost

#### Two Models:

- Lookup Model: Classic datastructure where requests originate at root
- <u>Routing Model</u>: Peer-to-peer communication



## **Our Contribution**

#### **Routing:**

- Static OBST:
  - A single additional BST can reduce costs from O(log n) to O(1)!
  - Entropy-based upper bounds on amortized communication costs
- Dynamic OBST:
  - Self-adjusting splay trees
  - Simulations
- Simulations

#### OBST: A Self-Adjusting Peer-to-Peer Overlay Based on Multiple BSTs

Chen Avin<sup>1</sup>, Michael Borokhovich<sup>1</sup>, Stefan Schmid<sup>2</sup> <sup>1</sup> Ben Gurion University, Beersheva, Israel; <sup>2</sup> TU Berlin & T-Labs, Berlin, Germany {avin, borokhovich}@cse.bgu.ac.il; stefan@net.t-labs.tu-berlin.de

Our Contributions. This paper initiates the study of

how to extend the splay tree concepts [5], [13] to multiple

trees, in order to design self-adjusting p2p overlays.

Concretely, we propose a distributed variant of the splay

tree to build the OBST overlay: in this overlay, frequently

communicating partners are located (in the static case) or

moved (in the dynamic case) topologically close(r), with-

out sacrificing local routing benefits: While in a standard

binary search tree (BST) a request always originates at the

root (we will refer to this problem as the *lookup problem*).

in the distributed BST variant, any pair of nodes in the

network can communicate; we will refer to the distributed

variant as the routing problem

Abstract—The design of scalable and robust overlay topologies has been a main research subject since the very origins of peer-to-peer (p2p) computing. Today, the corresponding optimization tradeoffs are fairly well-understood, at least in the static case and from a worst-case perspective.

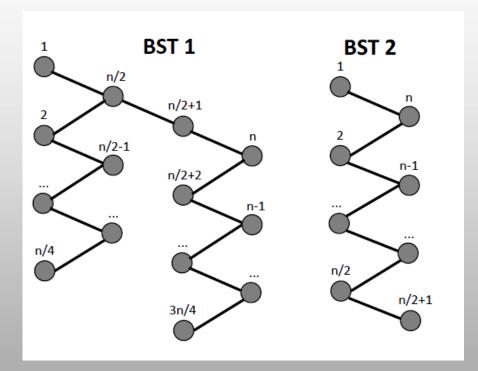
This paper revisits the peer-to-peer topology design problem from a self-organization perspective. We initiate the study of topologies which are optimized to serve the communication demand, or even self-adjusting as demand changes. The appeal of this new paradigm lies in the opportunity to be able to go beyond the lower bounds and limitations imposed by a static, communication-oblivious, topology. For example, the goal of having short routing paths (in terms of hop count) does no longer conflict with the requirement of having low peer degrees.

We propose a simple overlay topology OBST(k) which

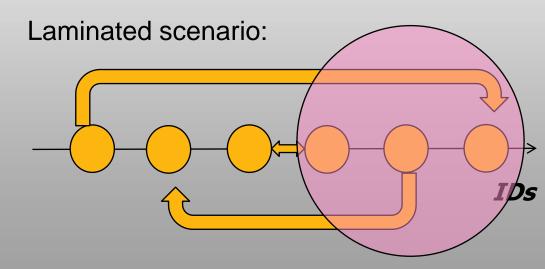
#### Lookup:

- Static OBST:
  - OBST(k) can only improve by additive –log(k) compared to OBST(1)

## Routing: OBST(2) vs OBST(1)



- Easy to embed in two BSTs: one for each (cost O(1))
- Hard to embed in one BST: because large interval cut ("crossing-matching")

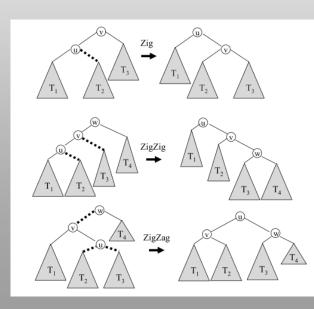


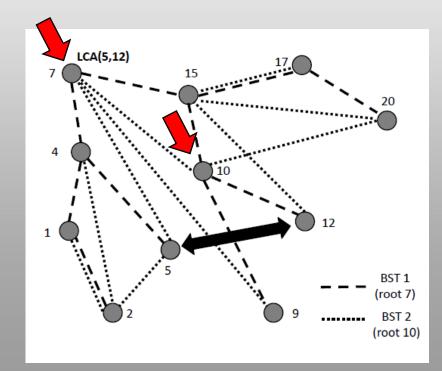
# Self-Adjusting OBST

#### Algorithm 1 Dynamic OBST(k)

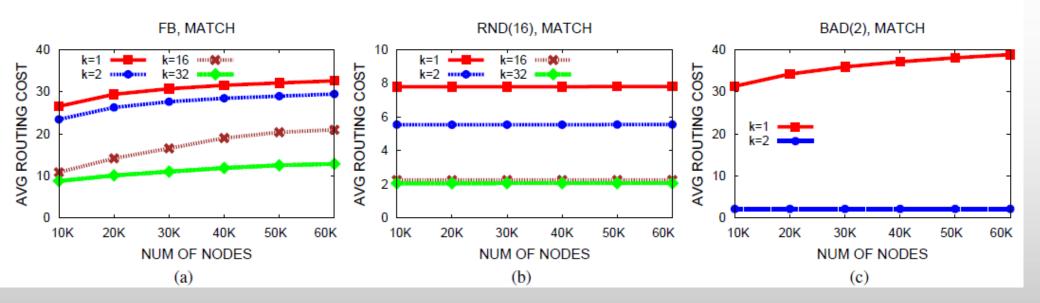
- 1: (\* upon request (u, v) \*)
- 2: find BST  $T \in OBST$  where u and v are closest;
- 3:  $w := LCA_T(u, v);$
- 4: T' := splay u to root of T(w);
- 5: splay v to the child of T'(u);

- Splay to Least Common Ancestor (more local!)...
- ... in best tree!





# Simulation



- Initially: k independent, random BSTs
- Communication models: matching and random walk
- (a) More trees help
- (b) On Random Graph relatively stable, almost perfect convergence
- (c) OBST(2) convergence to perfect tree for "bad example"

#### Churn

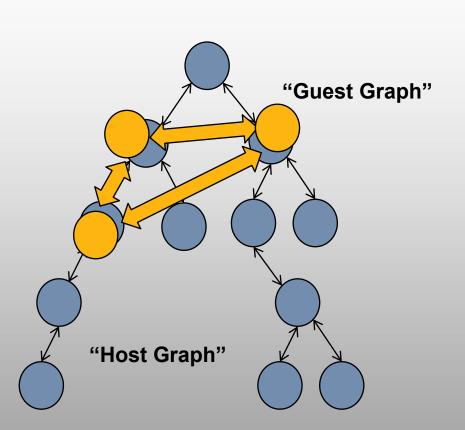
RND(16), MATCH, k=16, n=10000 AVG ROUTING COST λ

- Routing cost under  $\lambda$  joins/leaves between a lookup operation
- More plots in full paper...

## Conclusion

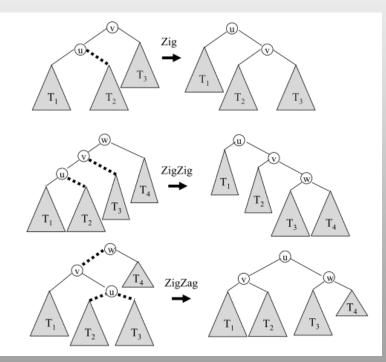
- Vision: self-adjusting networks
- Interesting generalization of Splay trees
- SplayNets
  - Formal analysis reveals nice properties
  - Amortized costs good: but tight?
  - Competitive ratio remains open
- OBST: lookup vs routing

## Thank you! Questions?



#### Algorithm 2 Double Splay Algorithm DS

- 1: (\* upon request (u, v) in T \*)
- 2:  $w := \alpha_T(u, v)$
- 3: T' := splay u to root of T(w)
- 4: splay v to the child of T'(u)



#### **Advertisement**



The Workshop on Distributed Cloud Computing (DCC 2013) will be co-located with IEEE/ACM Conference on Utility and Cloud Computing (UCC): December 9, 2013, Dresden, Germany

#### News

- [August 22, 2013] Rick McGeer, Distinguished Technologist at HP Enterprise Services, will give the keynote address
- [August 2, 2013] EasyChair submission closed
- · [July 8, 2013] EasyChair submission open
- [June 1, 2013] Website online

#### Dates

- · Submissions due: 2 August 2013 (hard!)
- Notification of acceptance: 10 September 2013
- Camera-ready papers due: 27 September 2013
- Workshop: 9 December 2013
- IEEE/ACM UCC Conference: 9-12 December 2013

#### Peer-to-Peer and the Cloud!

# Keynote by Rick McGeer, papers by Jen Rexford, Holger Karl, Christof Fetzer, Pietro Michardi, etc.

## Backup: The Optimal Offline Solution

#### Dynamic program

- Binary search: decouple left from right!
- Polynomial time (unlike MLA!)
- So: solved M"BST"A

#### See also:

 Related problem of phylogenetic trees

